

# TAM 674

## Applied Multibody Dynamics

Spring Term 2003, Mon & Wed 10:10-11:00, 202 Thurston Hall, 3 credits.

### Homework assignment 7

Determine the motion of the double pendulum from assignment 1 by numerical integration of the equations of motion as derived in assignment 5 or 6. The initial conditions are both bars vertically up at zero speed. We assume a gravitational field operating in the *horizontal* direction with a field strength of  $g = 9.81$  N/kg. We want to determine the angle, in radians, of both bars with respect to the horizontal axis after 5 seconds with a maximal absolute error of  $10^{-5}$  rad. Try and find the accordingly maximum step size for the following numerical integration methods:

1. Euler.
2. Heun.
3. Runge-Kutta 3<sup>rd</sup> order.
4. Classic Runge-Kutta 4<sup>th</sup> order.
5. Euler for second order differential equations.

Use the error estimate method as explained in the course and plot the  $\log_{10}$ (estimated error) versus the  $\log_{10}$ (step size) for all different applied methods in one figure.

Now use the ODE solvers `ode23`, `ode45`, and `ode113` from Matlab. Set the error tolerance `RelTol` and `AbsTol` accordingly and integrate the equations of motion from  $t = 0$  until  $t = 5$  seconds. Compare the angle of both bars with the results from above and determine the average step size and the total number of function evaluations (calls to  $f(t,y)$ ) as used in the three methods. Do these agree with your previous results? Please discuss.

### References

- [1] P. Henrici. *Discrete variable methods in ordinary differential equations*. Wiley, New York, 1962.
- [2] C. W. Gear. *Numerical initial value problems in ordinary differential equations*. Prentice-Hall, Englewood Cliffs, N.J., 1971.
- [3] L. F. Shampine and M. K. Gordon. *Computer solution of ordinary differential equations: the initial value problem*. W. H. Freeman, San Francisco, 1975.
- [4] J. C. Butcher. *The numerical analysis of ordinary differential equations: Runge-Kutta and general linear methods*. J. Wiley, Chichester, New York, 1987.
- [5] J. H. Hubbard and B. H. West. *Differential Equations: A Dynamical System Approach, Part 1, Ordinary Differential Equations*. Number 5 in Texts in Applied Mathematics. Springer, New York, 1991.
- [6] E. Hairer, S. P. Nørsett, and G. Wanner. *Solving Ordinary Differential Equations I: Nonstiff Problems*. Number 8 in Springer Series in Computational Mathematics. Springer-Verlag, Berlin Heidelberg, second revised edition, 1993.
- [7] L. F. Shampine. *Numerical solution of ordinary differential equations*. Chapman & Hall, New York, 1994.
- [8] E. Eich-Soellner and C. Führer. *Numerical Methods in Multibody Dynamics*. European Consortium for Mathematics in Industry. B.G.Teubner, Stuttgart, 1998.
- [9] R. von Schwerin. *Multibody System Simulation: Numerical Methods, Algorithms, and Software*. Number 7 in Lecture Notes in Computational Science and Engineering. Springer-Verlag, 1999.